

# Solutions to Quiz 2, 2019

## Problem 1

Use the Bio-Savart law,

$$d\mathbf{H} = \frac{I d\mathbf{l} \times \mathbf{R}}{4\pi R^3}, \quad (1)$$

1) Consider the horizontal arms first. On those arms,  $I d\mathbf{l} = I dx \mathbf{a}_x$  and  $\mathbf{R} = \pm x \mathbf{a}_x$ . It follows at once from Eq. 1 that since  $I d\mathbf{l} \times \mathbf{R} = 0$ , we have no contribution to the field at the center due to the horizontal arms.

2) Consider now the semi-circle. On the semi-circle,  $I d\mathbf{l} = -I b d\phi \mathbf{a}_\phi$ . The minus sign comes from the fact that the positive direction of  $\mathbf{a}_\phi$  is counterclockwise. Next,  $\mathbf{R} = b \mathbf{a}_\rho$  and  $R = b$ . It then follows from Eq.1 that

$$d\mathbf{H} = \frac{-I b d\phi (\mathbf{a}_\phi \times \mathbf{a}_\rho) b}{4\pi b^3} = \frac{I d\phi}{4\pi b} \mathbf{a}_z. \quad (2)$$

Thus,

$$\mathbf{H} = \int_{\pi}^0 d\phi \frac{I}{4\pi b} \mathbf{a}_z = -\frac{I}{4b} \mathbf{a}_z. \quad (3)$$

The limits of integration correspond to going from the left to the right end of the semi-circle. The minus sign in Eq. 2 implies that the field is directed into the plane of the loop.

## Problem 2

1) Method I. Working in the spherical coordinates,

$$\mathbf{B} = \nabla \times \mathbf{A} = \frac{1}{r^2 \sin \theta} \begin{vmatrix} \mathbf{a}_r & r \mathbf{a}_\theta & r \sin \theta \mathbf{a}_\phi \\ \partial_r & \partial_\theta & \partial_\phi \\ 0 & 0 & \frac{1}{2} r^2 \sin^2 \theta \end{vmatrix} = \mathbf{a}_r \cos \theta - \mathbf{a}_\theta \sin \theta.$$

2) Method II. Alternatively, observing that  $\mathbf{A} = \frac{1}{2} \rho \mathbf{a}_\phi$ , we can work in the cylindrical coordinates,

$$\mathbf{B} = \nabla \times \mathbf{A} = \frac{1}{\rho} \begin{vmatrix} \mathbf{a}_\rho & \rho \mathbf{a}_\phi & \mathbf{a}_z \\ \partial_\rho & \partial_\phi & \partial_z \\ 0 & \frac{1}{2} \rho^2 & 0 \end{vmatrix} = \mathbf{a}_z.$$

The two answers are equivalent as can be readily inferred from your formula sheet.

### Problem 3

a) By definition,  $I = \int d\mathbf{S} \cdot \mathbf{J}$ . In this case,  $d\mathbf{S} = R d\phi dz \mathbf{a}_\rho$  on the cylindrical surface. It follows that

$$I = \int_0^L dz \int_0^{2\pi} d\phi (\mathbf{a}_\rho \cdot \mathbf{a}_\rho) R J_0 (R/R) = 2\pi R L J_0.$$

b) The divergence of the current density reads,

$$\nabla \cdot \mathbf{J} = \frac{1}{\rho} \partial_\rho (\rho J_\rho) = \frac{1}{\rho} \partial_\rho \left( J_0 \frac{\rho^2}{R} \right) = 2J_0/R. \quad (4)$$

The continuity equation implies that

$$\partial_t \rho_v = -\nabla \cdot \mathbf{J} = -2J_0/R. \quad (5)$$

It follows by integrating Eq. 5 that

$$\rho_v(\mathbf{r}, t) = \rho_v(\mathbf{r}, 0) - 2J_0 t/R = \rho_{v0} - 2J_0 t/R. \quad (6)$$

c) It follows at once from Eq. 6 that the current density vanishes at the finite time

$$t_* = \frac{\rho_{v0} R}{2J_0}.$$